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1. $X \in \mathbb{R}^d$ has a spherical distribution.
2. There exists a function $\psi: \mathbb{R} \rightarrow \mathbb{R}$ of a scalar variable, such that the characteristic function of X satisfies

$$\phi_X(t) = \psi(t^T t) = \psi(t_1^2 + t_2^2 + \dots + t_d^2)$$

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3. For every vector $a \in \mathbb{R}^d$, $a^t X \stackrel{d}{=} \|a\| X_1$ holds, where $\|a\|^2 = a_1^2 + a_2^2 + \dots + a_d^2$.

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3. For every vector $a \in \mathbb{R}^d$, $a^t X \stackrel{d}{=} \|a\| X_1$ holds, where $\|a\|^2 = a_1^2 + a_2^2 + \dots + a_d^2$.
4. X has the stochastic representation $X \stackrel{d}{=} RS$, where $S \in \mathbb{R}^d$ is a random vector uniformly distributed on the unit sphere S^{d-1} , $S^{d-1} := \{x \in \mathbb{R}^d : \|x\| = 1\}$, and $R \geq 0$ is a r.v. independent of S .

Notation: $X \sim S_d(\psi)$, cf. 2.

Spherical distributions (contd.)

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Example: The standard normal distribution is a spherical distribution.

Let $X \sim N_d(0, I)$. Then $X \sim S_d(\psi)$ mit $\psi = \exp(-x/2)$.

Indeed, $\phi_X(t) = \exp\{it^T 0 - \frac{1}{2}t^T I t\} = \exp\{-t^T t/2\} = \psi(t^T t)$, and thus X has a spherical distribution.

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Let $X = RS$ be the stochastic representation of $X \sim N_d(0, I)$. Then

$$\|X\|^2 \stackrel{d}{=} R^2 \sim \chi_d^2;$$

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Simulation of a spherical distribution:

- (i) Simulate s from S which is uniformly distributed on the unit sphere S^{d-1} (e.g. by simulating y from a multivariate standard normal distribution $Y \sim N_d(0, I)$ and then setting $s = y/\|y\|$).

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The characteristic function can be written as

$$\begin{aligned}\phi_X(t) &= E(\exp\{it^T X\}) = E(\exp\{it^T(\mu + AY)\}) \\ &= \exp\{it^T \mu\} E(\exp\{i(A^T t)^T Y\}) \\ &= \exp\{it^T \mu\} \psi(t^T \Sigma t),\end{aligned}$$

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If $A \in \mathbb{R}^{d \times d}$ is nonsingular, then we have the following relation between elliptical and spherical distributions:

$$X \sim E_d(\mu, \Sigma, \psi) \Leftrightarrow A^{-1}(X - \mu) \sim S_d(\psi), \quad A \in \mathbb{R}^{d \times d}, \quad AA^T = \Sigma.$$

Elliptical distributions (contd.)

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Theorem: (Stochastic representation of elliptical distributions)

Let $X \in \mathbb{R}^d$ be an d -dimensional random vector. $X \sim E_d(\mu, \Sigma, \psi)$ iff $X \stackrel{d}{=} \mu + RAS$, where $S \in \mathbb{R}^k$ is a random vector uniformly distributed on the unit sphere \mathcal{S}^{k-1} , $R \geq 0$ is a r.v. independent of S , $A \in \mathbb{R}^{d \times k}$ is a constant matrix with $\Sigma = AA^T$ and $\mu \in \mathbb{R}^d$ is a constant vector.

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Simulation of an elliptical distribution:

- (i) Simulate s from S which is uniformly distributed on the unit sphere \mathcal{S}^{d-1} (e.g. by simulating y from a multivariate standard normal distribution $Y \sim N_d(0, I)$ and then setting $s = y/\|y\|$).

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- (ii) Simulate r from R .
- (iii) Set $x = \mu + rAs$.

Examples of elliptical distributions

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- ▶ Multivariate normal distribution

Let $X \sim N(\mu, \Sigma)$ with Σ positive definite. Then for $A \in \mathbb{R}^{d \times k}$ with $AA^T = \Sigma$ we have $X \stackrel{d}{=} \mu + AZ$, where $Z \in N_k(0, I)$. Moreover $Z = RS$ holds with S being uniformly distributed on the unit sphere \mathcal{S}^{k-1} and $R^2 \sim \chi_k^2$. Thus $X \stackrel{d}{=} \mu + RAS$ holds and hence $X \sim E_d(\mu, \Sigma, \psi)$ with $\psi(x) = \exp\{-x/2\}$.

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- ▶ Multivariate normal variance mixtures

Let $Z \sim N_d(0, I)$. Then Z has a spherical distribution with stochastic representation $Z \stackrel{d}{=} VS$ with $V^2 = \|Z\|^2 \sim \chi_d^2$. Let $X = \mu + WAZ$ be a variance normal mixture distribution. Then we get $X \stackrel{d}{=} \mu + VWAS$ with $V^2 \sim \chi_d^2$ and VW is a nonnegative r.v. independent of S . Thus X is elliptically distributed with $R = VW$.

Properties of elliptical distributions

Theorem:

Let $X \sim E_k(\mu, \Sigma, \psi)$. X has the following properties:

- ▶ Linear transformation

For $B \in \mathbb{R}^{k \times d}$ and $b \in \mathbb{R}^k$ we have:

$$BX + b \in E_k(B\mu + b, B\Sigma B^T, \psi).$$

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- ▶ Marginal distributions

Set $X^T = \left(X^{(1)T}, X^{(2)T} \right)$ for $X^{(1)T} = (X_1, X_2, \dots, X_n)^T$ and

$X^{(2)T} = (X_{n+1}, X_{n+2}, \dots, X_k)^T$ and analogously set

$\mu^T = \left(\mu^{(1)T}, \mu^{(2)T} \right)$ as well as $\Sigma = \begin{pmatrix} \Sigma^{(1,1)} & \Sigma^{(1,2)} \\ \Sigma^{(2,1)} & \Sigma^{(2,2)} \end{pmatrix}$. Then

$X_1 \sim E_n\left(\mu^{(1)}, \Sigma^{(1,1)}, \psi\right)$ and $X_2 \sim E_{k-n}\left(\mu^{(2)}, \Sigma^{(2,2)}, \psi\right)$.

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- ▶ Conditional distributions

Assume that Σ is nonsingular. Then

$$X^{(2)} \Big| X^{(1)} = x^{(1)} \sim E_{d-k} \left(\mu^{(2,1)}, \Sigma^{(22,1)}, \tilde{\psi} \right) \text{ where}$$

$$\mu^{(2,1)} = \mu^{(2)} + \Sigma^{(2,1)} \left(\Sigma^{(1,1)} \right)^{-1} \left(x^{(1)} - \mu^{(1)} \right) \text{ and}$$

$$\Sigma^{(22,1)} = \Sigma^{(2,2)} - \Sigma^{(2,1)} \left(\Sigma^{(1,1)} \right)^{-1} \Sigma^{(1,2)}.$$

Typically $\tilde{\psi}$ is a different characteristic generator than the original ψ (see Fang, Katz and Ng 1987).

Properties of elliptical distributions (contd.)

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- ▶ Quadratic forms

If Σ is nonsingular, then $D^2 = (X - \mu)^T \Sigma^{-1} (X - \mu) \sim R^2$, where R is the nonnegative r.v. in the stochastic representation $Y = RS$ of the spherical distribution Y with $S \sim U\left(\mathcal{S}^{(d-1)}\right)$ and $X = \mu + AY$. The random variable D is called *Mahalanobis distance*.

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- ▶ Convolutions

Let $X \sim E_k(\mu, \Sigma, \psi)$ and $Y \sim E_k(\tilde{\mu}, \Sigma, \tilde{\psi})$ be two independent random vectors. Then $X + Y \sim E_k(\mu + \tilde{\mu}, \Sigma, \bar{\psi})$ where $\bar{\psi} = \psi \tilde{\psi}$.

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Note that the dispersion matrix Σ must be the same for X and Y .

Important: $X \sim E_k(\mu, I_k, \psi)$ does not imply that the components of X are independent. The components of X are independent iff X is multivariate normally distributed with the unit matrix as a covariance matrix.

Coherent risk measures

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(C4) Monotonicity:

$$\forall X_1, X_2 \in M \text{ the implication } X_1 \stackrel{\text{a.s.}}{\leq} X_2 \implies \rho(X_1) \leq \rho(X_2) \text{ holds.}$$

Convex risk measures

Consider the property:

(C5) Convexity:

$$\forall X_1, X_2 \in M, \forall \lambda \in [0, 1]$$

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Definition: A risk measure ρ in M with the properties (C1),(C4) and (C5) is called *convex* in M .

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$$\forall X_1, X_2 \in M, \forall \lambda \in [0, 1]$$

$$\rho(\lambda X_1 + (1 - \lambda)X_2) \leq \lambda \rho(X_1) + (1 - \lambda)\rho(X_2) \text{ holds.}$$

(C5) is weaker than (C2) and (C3), i.e. (C2) and (C3) together imply (C5), but not vice-versa.

Definition: A risk measure ρ in M with the properties (C1),(C4) and (C5) is called *convex* in M .

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Let the probability measure P be defined by some continuous or discrete probability distribution F .

$VaR_\alpha(F) = F^{\leftarrow}(\alpha)$ has the properties (C1), (C3) and (C4), whereas the subadditivity (C2) is not fulfilled in general.

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Theorem: Let (Ω, \mathcal{F}, P) be a probability space and $M \subseteq L^{(0)}(\Omega, \mathcal{F}, P)$ be the set of the random variables with a continuous distribution in (Ω, \mathcal{F}, P) . CVaR_α is a coherent risk measure in M , $\forall \alpha \in (0, 1)$.

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(C1),(C3), (C4) follow from $\text{CVaR}_\alpha(F) = \frac{1}{1-\alpha} \int_\alpha^1 \text{Var}_p(F) dp$.

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To show (C2) observe that for a sequence of i.i.d. r.v. L_1, L_2, \dots, L_n with order statistics $L_{1,n} \geq L_{2,n} \geq \dots \geq L_{n,n}$ and for any $m \in \{1, 2, \dots, n\}$

$$\sum_{i=1}^m L_{i,n} = \sup\{L_{i_1} + L_{i_2} + \dots + L_{i_m} : 1 \leq i_1 < \dots < i_m \leq n\} \text{ holds.}$$

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$$\min_{w \in \mathcal{P}_m} \rho(Z(w)) \tag{1}$$

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If $\rho = \text{VaR}_\alpha$, $\alpha \in (0, 1)$ we get the *mean-VaR pf. optimization model*

$$\min_{w \in \mathcal{P}_m} \text{VaR}_\alpha(Z(w)).$$

Question: What is the relationship between these three portfolio optimization models?